

RouteNet: Routability Prediction for Mixed-Size Designs Using Convolutional Neural Network

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Background

- Challenges in Routability Prediction:
 - Predict routability at placement stage
 - Predict by 'fast trial global routing'
 - Not fast enough
 - Predict locations of Design Rule Checking (DRC) hotspots
 - Predict by global routing
 - Not accurate enough

Background

- Our Attempt on Such Challenges:
 - Fast routability forecast for placement
 - In terms of number of Design Rule Violations (#DRV)
 - To identify more routable placements among many candidates
 - Prediction of DRC hotspot locations
 - To proactively modify solutions to prevent design rule violations

Background

- Previous solutions:
 - Many fail to consider macros
 - Some require Global Routing information for #DRV prediction

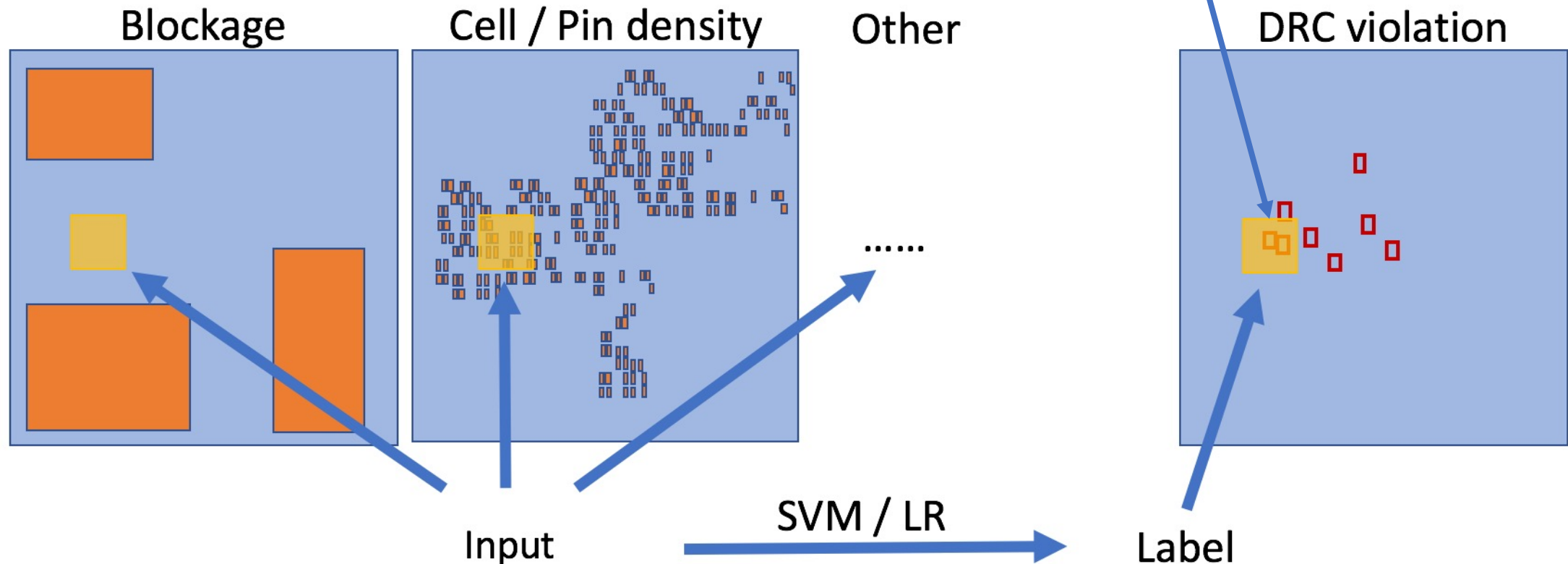
Methods		Use GR?	Predict #DRV?	Predict hotspot?	Handle macros?
[18] (Qi, et al., ICCD14)		Y	Y	N	Y
[26] (Zhou, et al., ASQED15)		Y	Y	N	N
[3] (Chan, et al., ICCD16)		N	Y	N	N
[4] (Chan, et al., ISPD17)		Y	N	Y	N
Our Method {	RouteNet #DRV prediction	N	Y	N	Y
	RouteNet hotspot prediction	Y	N	Y	Y

GR means global routing

#DRV means number of DRC violations

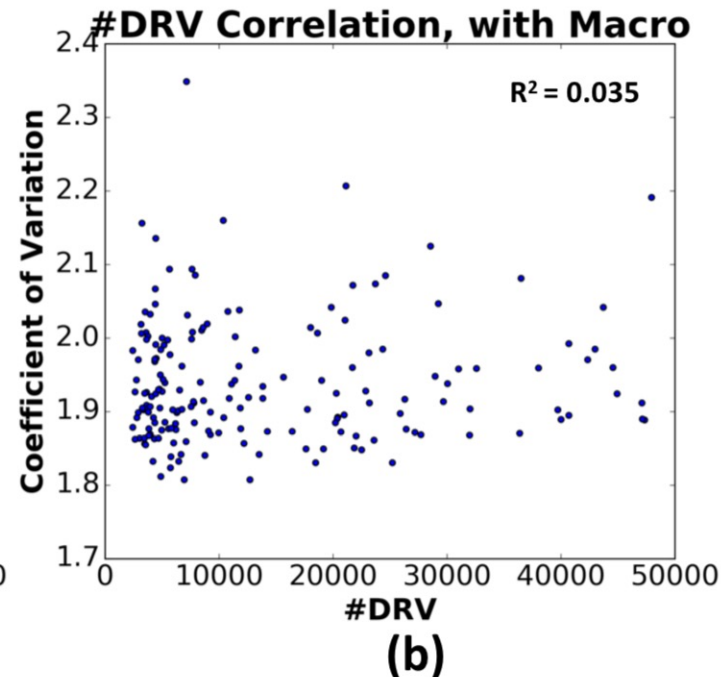
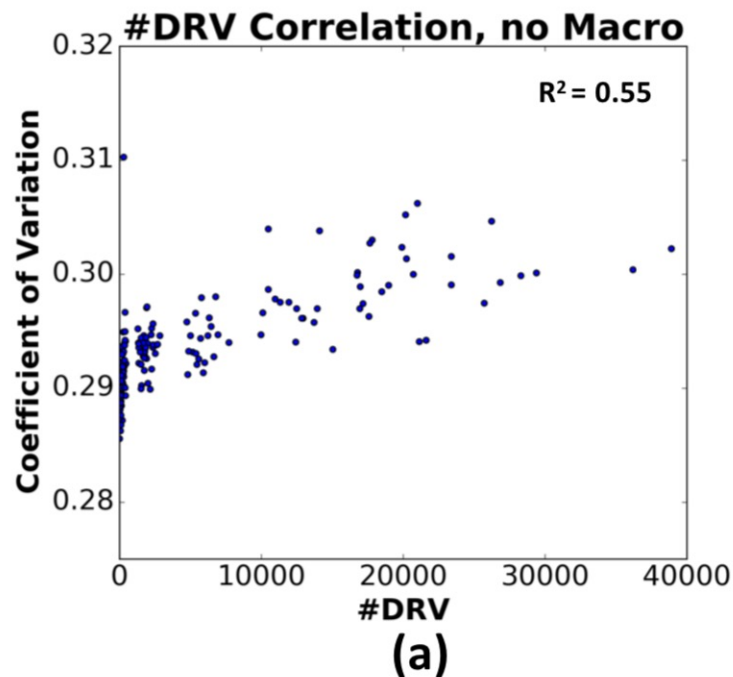
Background

- Previous solutions:
 - Many apply machine learning on every *small cropped region*



Background

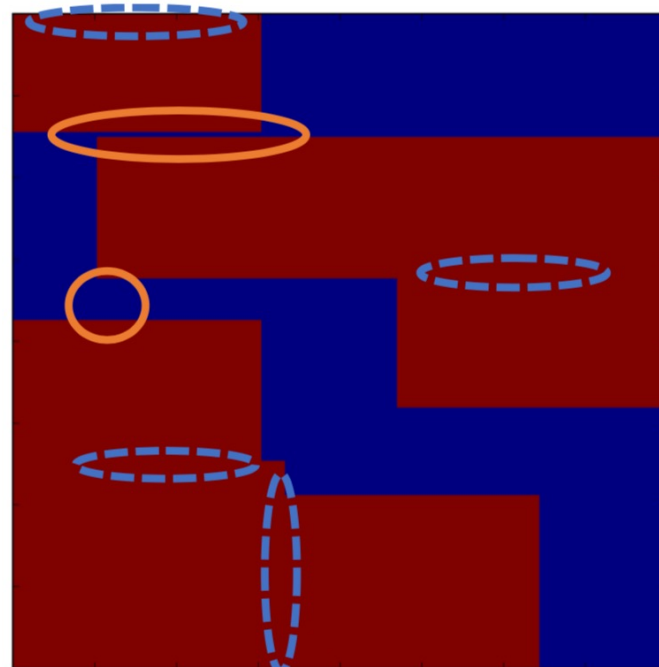
- Challenges of Macros on #DRV prediction:
 - Correlation between pin density and #DRV largely disappears with macro



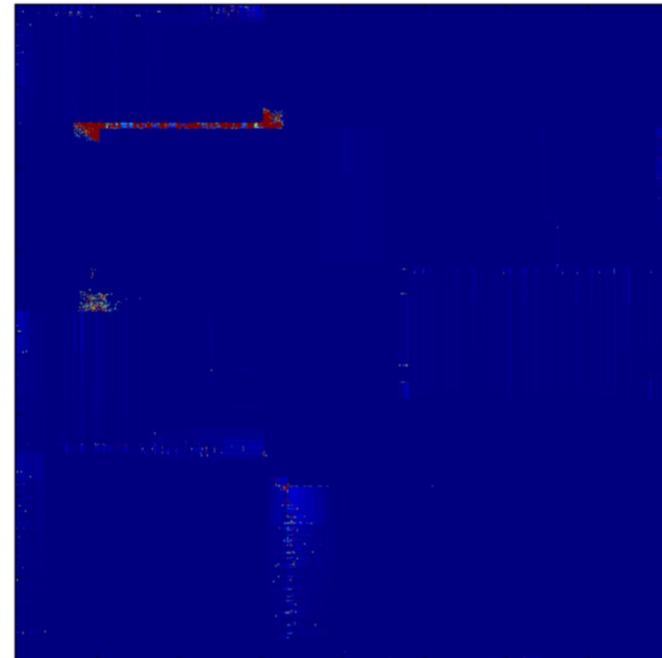
Correlation between #DRV and coefficient of variation ($\frac{\sigma}{\mu}$) of pin density. Each point corresponds to one placement.

Background

- Challenges of Macros on hotspot detection:
 - Hotspots tend to aggregate at small gaps between neighboring macros



Macros



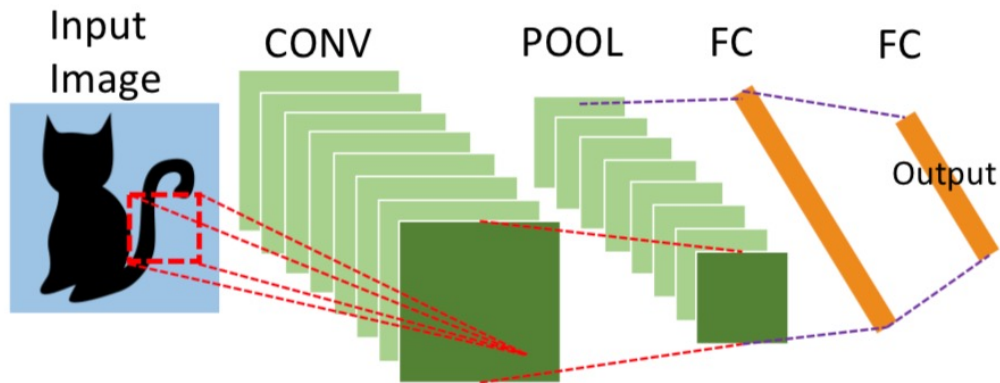
DRC hotspot

Background

- Challenges of Macros:
 - A layout with macros is much less **homogeneous**
 - **Homogeneity** implies resemblance among different regions of layout
 - Need a larger region to capture global view
 - **Use deep neural network!**

Background

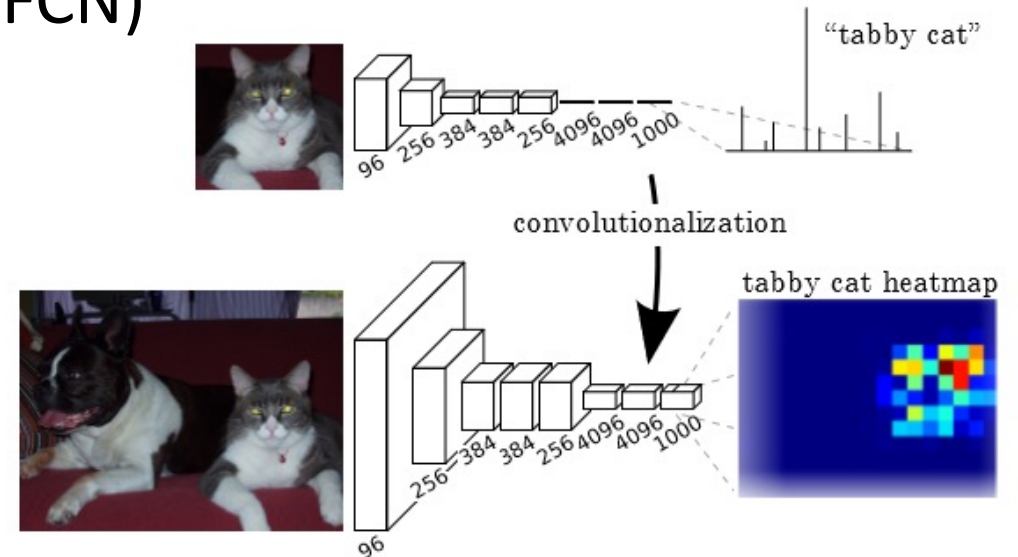
- Convolutional Neural Network (CNN)



Convolutional (CONV), Pooling (POOL) and Fully Connected (FC) layers

Widely used in image classification

- Fully Convolutional Network (FCN)



Eliminate FC layers

May use transposed-convolution to up-sample

Used in image segmentation, object detection

Features Extraction

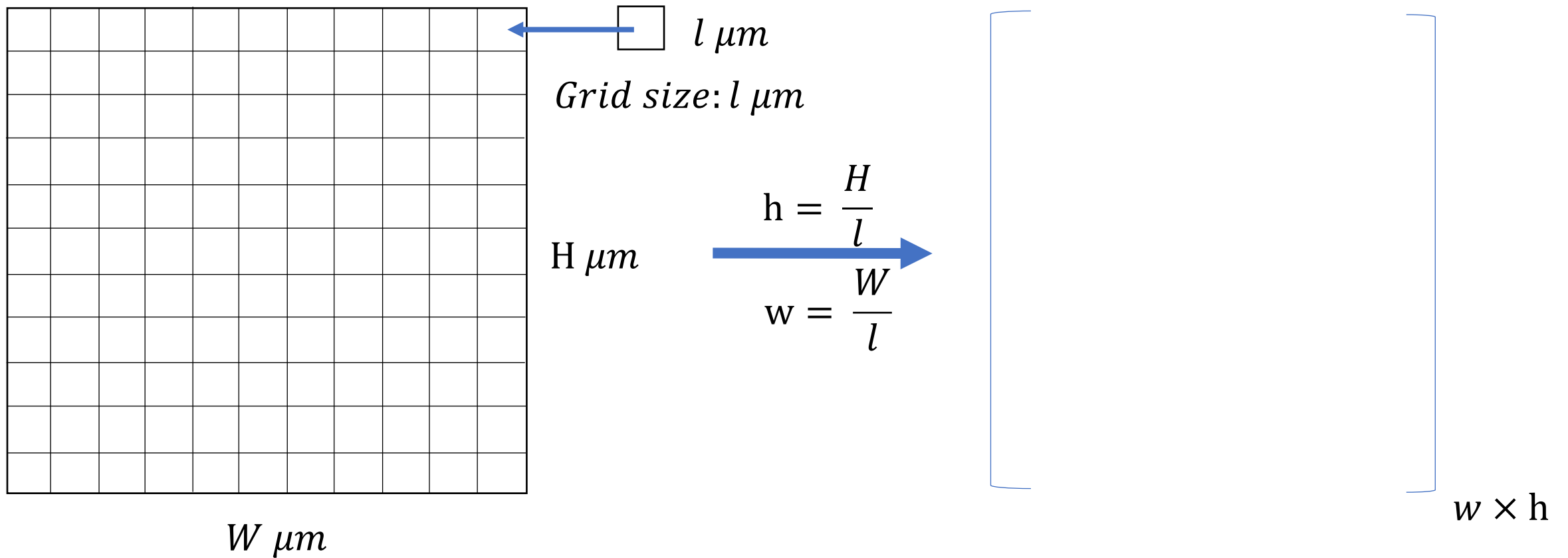
- RUDY (Rectangular Uniform wire DensitY) (P. Spinder et al. 2007)
 - RUDY is a pre-routing congestion estimator
 - At (x, y) , for k th net with bounding box $\{x_{min}^k, x_{max}^k, y_{min}^k, y_{max}^k\}$:

$$w^k = x_{max}^k - x_{min}^k, h^k = y_{max}^k - y_{min}^k$$
$$c^k = \begin{cases} 1 & x \in [x_{min}^k, x_{max}^k], y \in [y_{min}^k, y_{max}^k] \\ 0 & otherwise \end{cases}$$
$$RUDY^k(x, y) \propto c^k \frac{w^k + h^k}{w^k \times h^k} \quad \leftarrow \frac{\text{Half perimeter}}{\text{area}}$$

$$RUDY(x, y) = \sum_{k=1}^K RUDY^k(x, y) \quad \leftarrow \text{Sum up all nets}$$

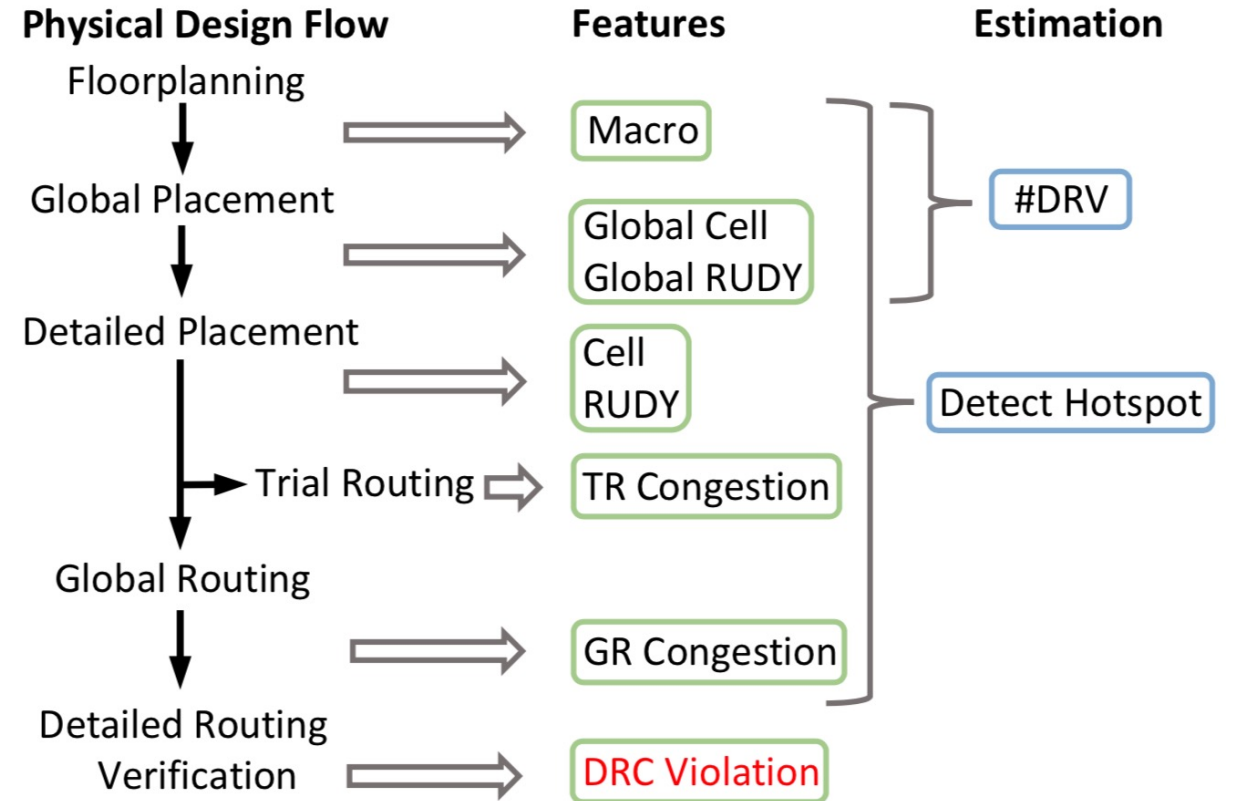
Features Extraction

- X_{ij} = j th feature in i th placement



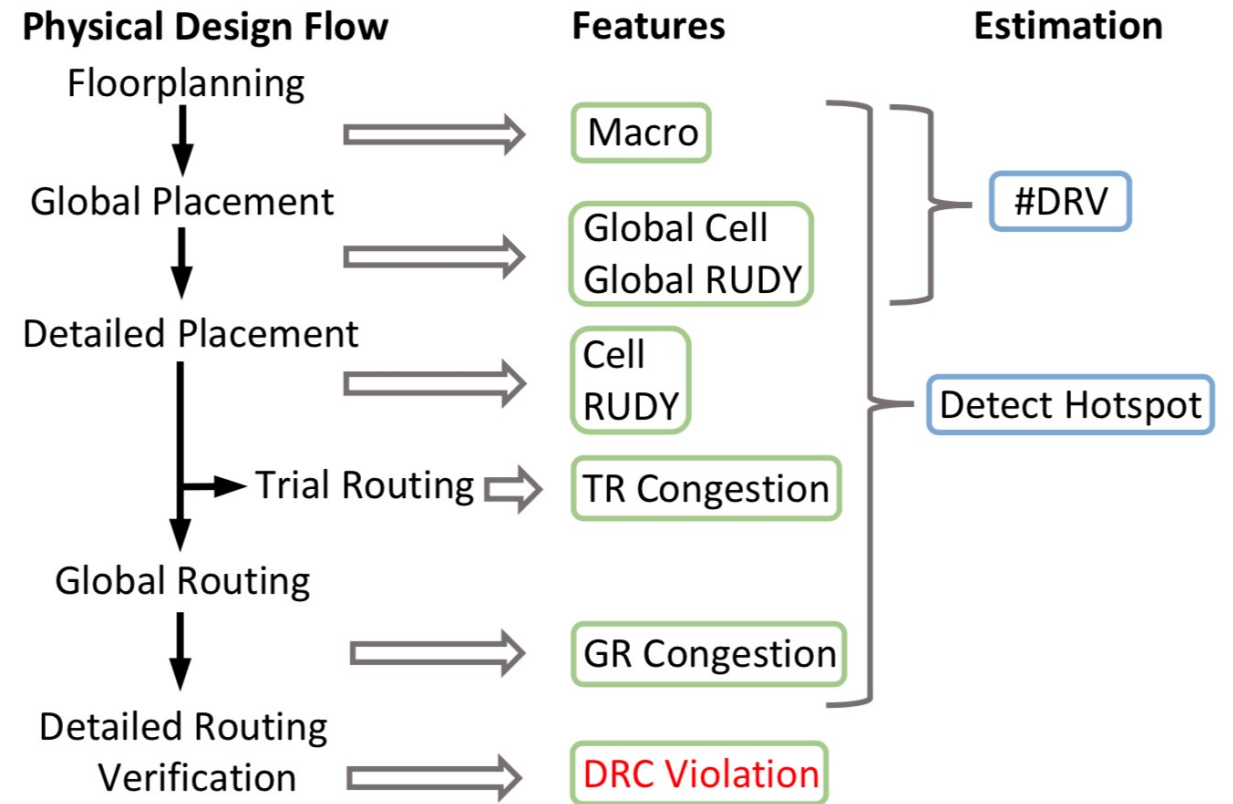
Features Extraction

- Macro:
 - region occupied by macros
 - density of macro pins in each layer
- Cell:
 - density of cells
 - density of cell pins
- Global cell:
 - cell features at global placement
- Global RUDY:
 - RUDY features calculated by global placement results



Features Extraction

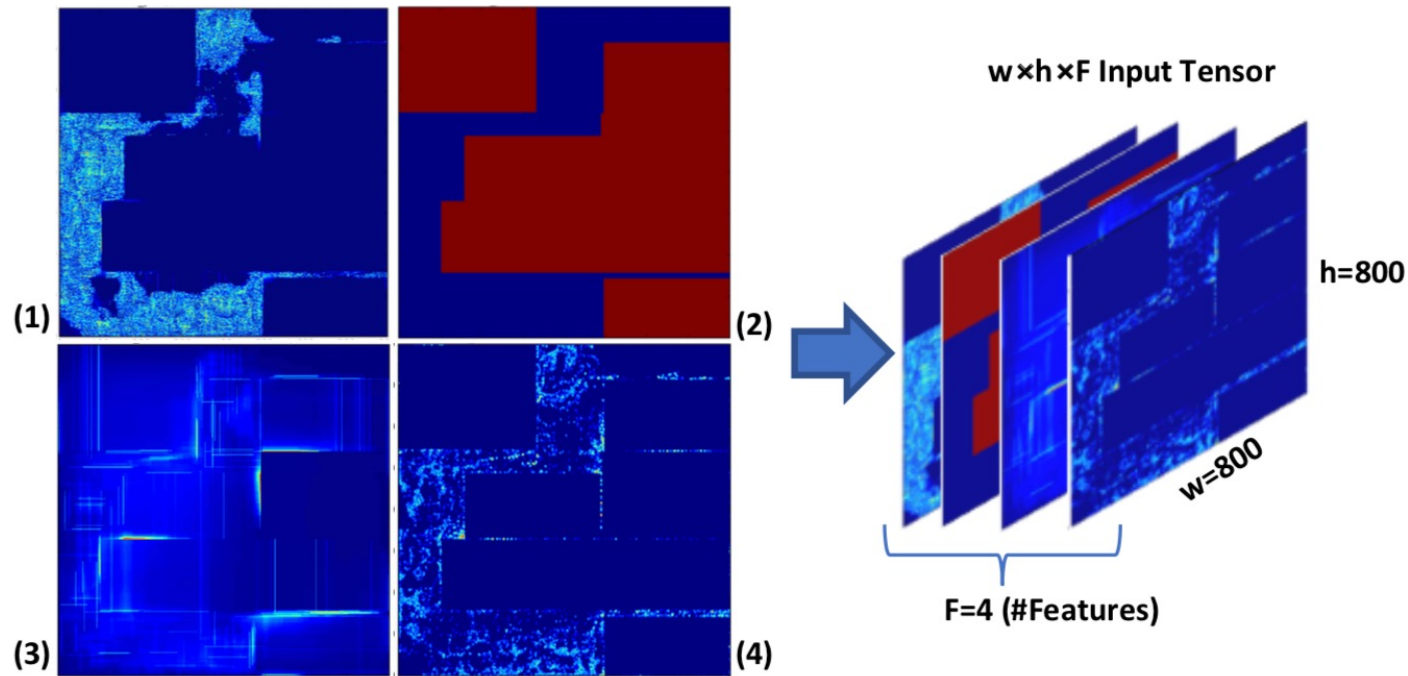
- RUDY
 - long-range RUDY
 - RUDY from long-range nets
 - short-range RUDY
 - DURY from short-range nets
 - RUDY pins
 - pins with density value equal to the RUDY value of its net
- Congestion
 - trial global routing congestion
 - global routing congestion
- DRC violation
 - prediction target / label



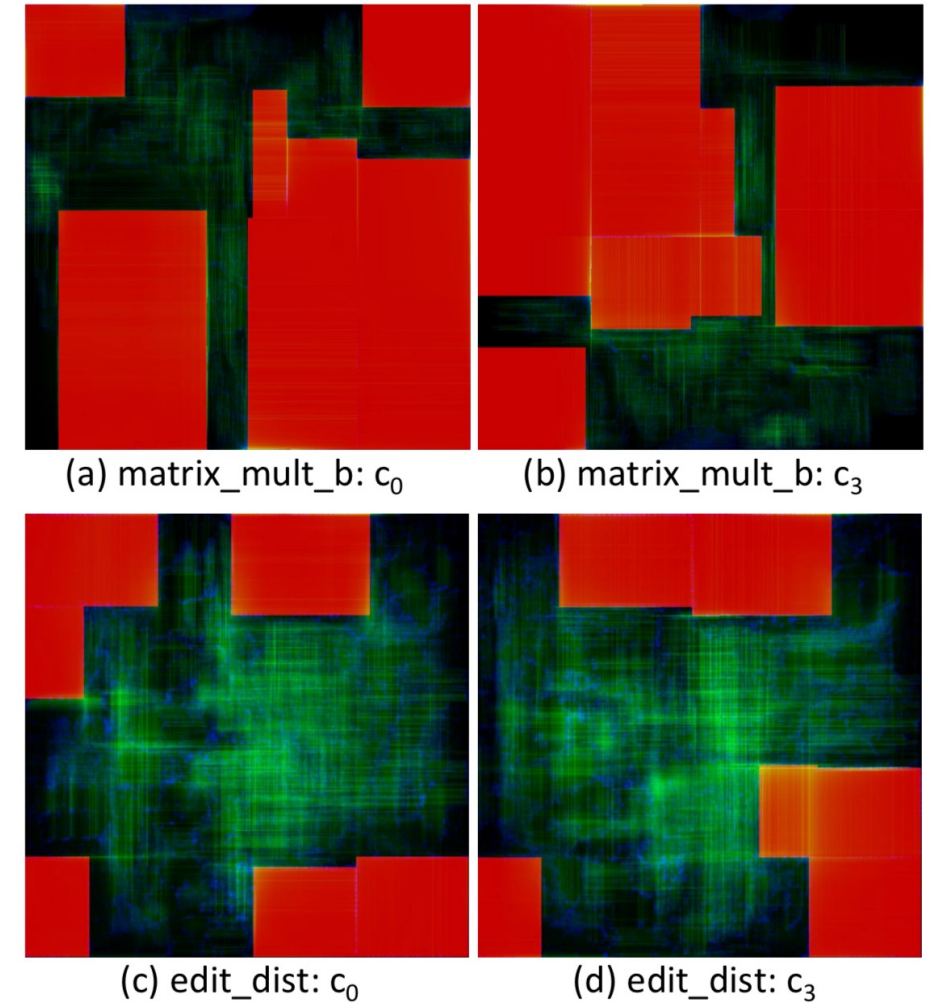
For i^{th} placement with size $w \times h$ and F features:

$$X_i \in \mathbb{R}^{w \times h \times F}$$

Features Extraction



Input tensor constructed by stacking 2D features:
(1) Pin density, (2) macro (3) long-range RUDY, (4) RUDY pins



Input features for #DRV prediction.
Red: macro region
Green: global long-range RUDY
Blue: global RUDY pins

Proposed Model

Problem 1 (#DRV prediction). Find an estimator $f_{\#DRV}^*$ of DRV count in a placement:

$$f_{\#DRV} : X_i^{(\#DRV)} \in \mathbb{R}^{w \times h \times F_1} \rightarrow y_i \in \mathbb{N}$$

$$f_{\#DRV}^* = \arg \min_f \text{Loss}(f(X_i^{(\#DRV)}), y_i)$$

Convolutional Neural Network
(CNN)

Problem 2 (Hotspot prediction). Find a detector $f_{hotspot}^*$ of hotspots. It reports locations of all DRC hotspots in a placement.

$$f_{hotspot} : X_i^{(hotspot)} \in \mathbb{R}^{w \times h \times F_2} \rightarrow V_i \in \{0, 1\}^{w \times h}$$

$$f_{hotspot}^* = \arg \min_f \text{Loss}(f(X_i^{(hotspot)}), V_i)$$

$$Y_i \in \mathbb{R}^{w \times h} \quad V_{i_{mn}} = \mathbb{1}(Y_{i_{mn}} > \epsilon)$$

Fully Convolutional Network
(FCN)

Proposed Model- #DRV Prediction

Algorithm 1 Algorithm of RouteNet for #DRV Prediction

Input: Number of training placements: N , Features:

$\{X_i \in \mathbb{R}^{w \times h \times 3} \mid i \in [1, N]\}$, Targets: $\{y_i \in \mathbb{R} \mid i \in [1, N]\}$

Preprocess:

1: **for** each int $i \in [1, N]$ **do**
2: Resize $X_i \in \mathbb{R}^{w \times h \times 3}$ into $X_i^{\#DRV} \in \mathbb{R}^{224 \times 224 \times 3}$

3: Find 25%, 50%, 75% quantizes of y_i : q_1, q_2, q_3

4: **for** each int $i \in [1, N]$ **do**

5: $C_i \leftarrow 0$

6: **for** each int $t \in [1, 3]$ **do**

7: **if** $y_i > q_t$ **then**

8: $C_i \leftarrow t$, **break**

9: Form dataset $\{(X_i^{\#DRV}, C_i) \mid i \in [1, N]\}$

10: Training set $\{(X_i^{\#DRV}, C_i) \mid C_i = 0 \text{ or } C_i = 3\}$

Training:

1: Get pretrained ResNet18 $f_{Res} : \mathbb{R}^{224 \times 224 \times 3} \rightarrow \mathbb{R}^{1000}$

2: Replace output layer, s.t. $f_{\#DRV} : \mathbb{R}^{224 \times 224 \times 3} \rightarrow \mathbb{R}$

3: Choose MSE as loss function, SGD for optimization

4: Train $f_{\#DRV}$ with preprocessed dataset for ~ 30 epochs

Output: $f_{\#DRV}$ estimating #DRV level

Resize input to 224×224 , to
utilize models pre-trained on
images with size 224×224

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Assign placements to 4 different classes (c_0, c_1, c_2, c_3) based on their level of violations (#DRV)

c_0 represents least #DRV, while c_3 represents most

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Download a pre-trained CNN model named ResNet18



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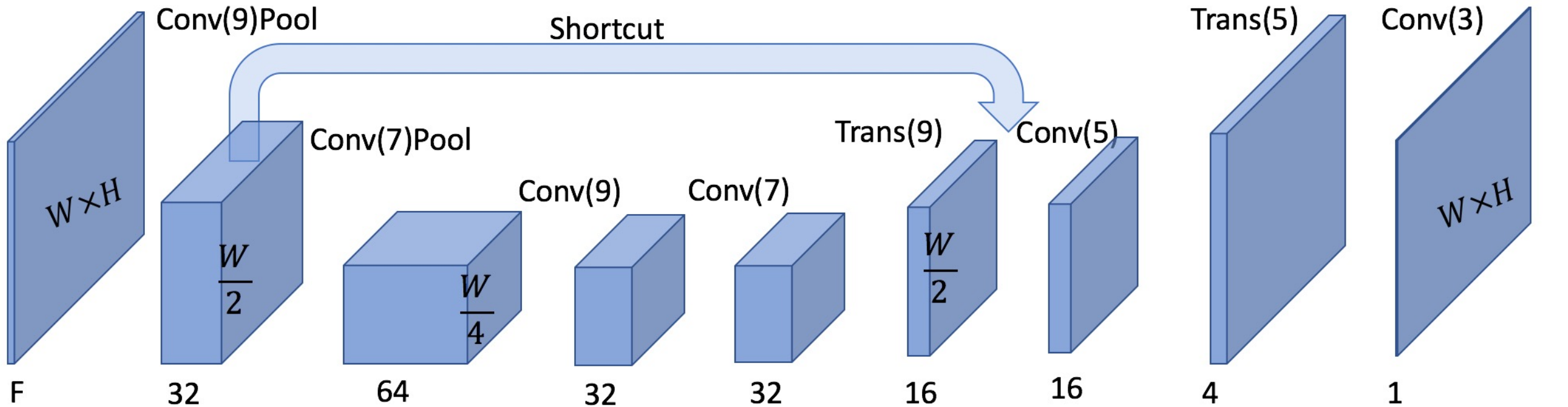
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← Fine-tune CNN with preprocessed data

Proposed Model- Hotspot Detection



$$Y_{i_{mn}}^{clip} = \min(Y_{i_{mn}}, c)$$

$$Loss = \sum_{i=1}^N \sum_{m=1}^w \sum_{n=1}^h ||f_{hotspot}(X_{i_{mn}}) - Y_{i_{mn}}^{clip}||_2 + \lambda ||W||_2$$

Pixel-wise loss function

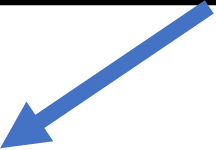
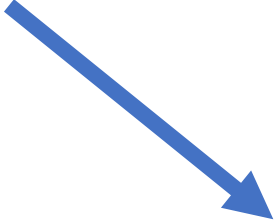
Data

- Five designs from ISPD 2015
- ~300 different placements by placing macros in different way
- When each design tested, model trained only on four other designs
- SVM and Logistic Regression (LR) methods for comparison

Circuit Name	#Macros	#Cells	#Nets	Width (μm)	#Placements
des_perf	4	108288	110283	900	600
edit_dist	6	127413	131134	800	300
fft	6	30625	32088	800	300
matrix_mult_a	5	149650	154284	1500	300
matrix_mult_b	7	146435	151614	1500	300

#DRV Prediction Evaluation

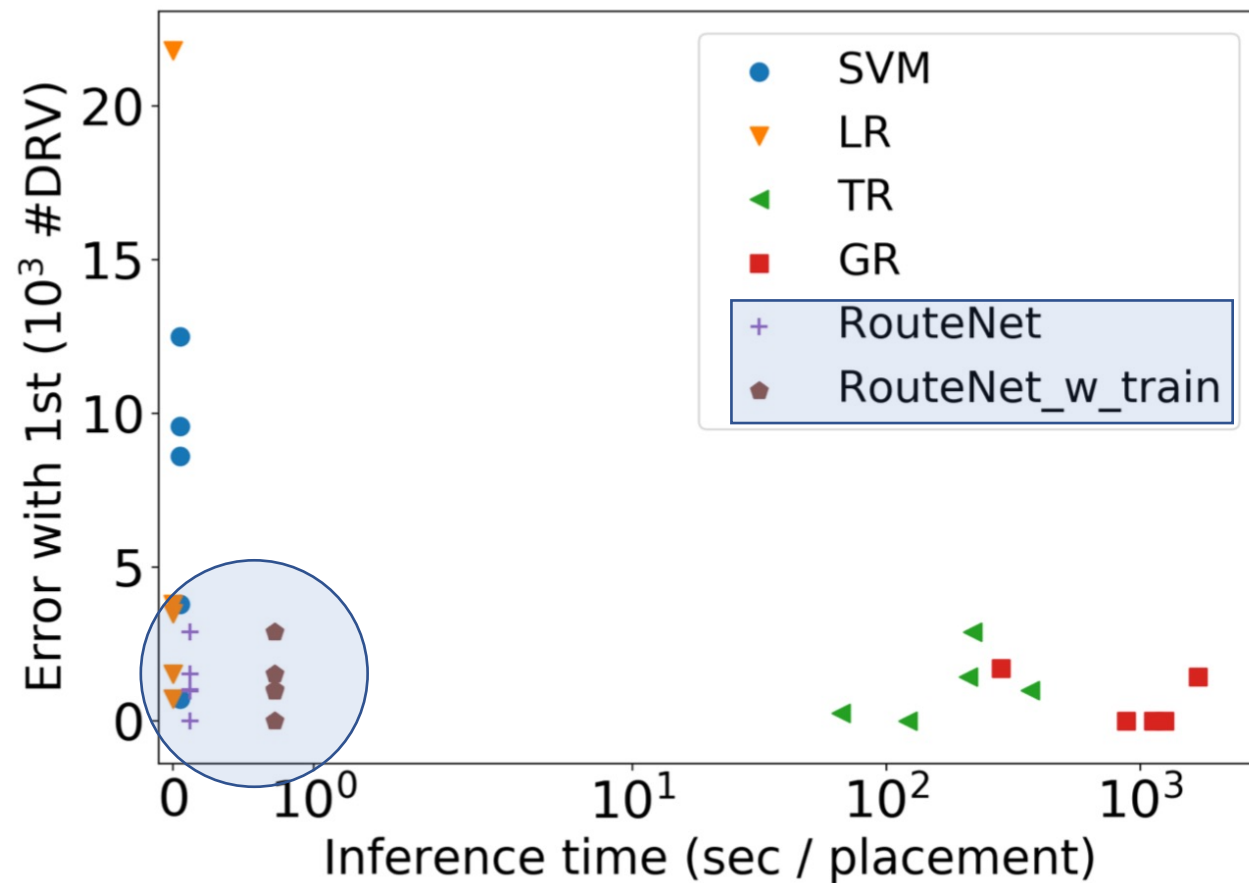
- How methods recognize placements with the lowest #DRV level (c_0)
- The quality of placements selected by each method
 - The **best rank** of top ten placements predicted to have least #DRV



Circuit Name	$c_0/c_1+c_2+c_3$ accuracy (%)					Best rank in top 10				
	SVM	LR	TR	GR	Route Net	SVM	LR	TR	GR	Route Net
des_perf	63	74	80	77	80	87 th	15 th	2 nd	1 st	2 nd
edit_dist	69	68	78	77	76	17 th	17 th	3 rd	3 rd	2 nd
fft	66	62	73	70	75	6 th	6 th	2 nd	33 rd	1 st
matrix_mult_a	66	65	78	74	72	30 th	5 th	1 st	1 st	5 th
matrix_mult_b	63	62	76	73	76	22 nd	93 rd	4 th	1 st	4 th
Average	65	66	77	74	76	32 nd	27 th	2 nd	8 th	3 rd

#DRV Prediction Evaluation

- Y: gap between the 'best in 10' and the actually 1st-ranked placement with least #DRV
- X: inference time taken for each method
- RouteNet achieves low inference time and high accuracy at the same time



DRC Hotspot Detection Evaluation

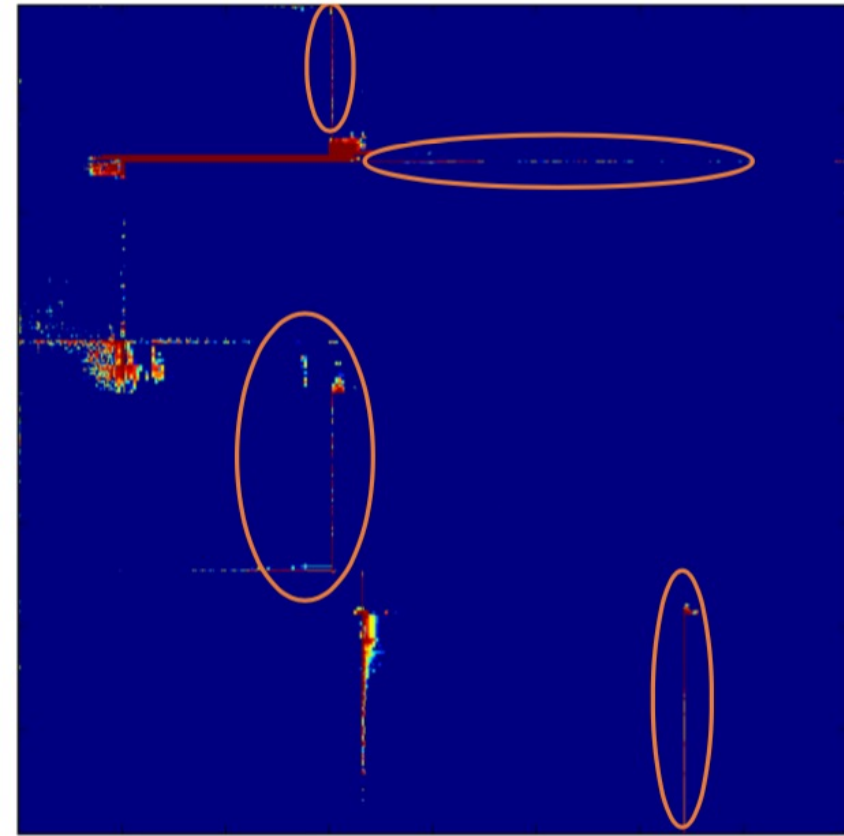
- Same decision threshold is used for all designs
- Slight different FPR, but all under 1%
- RouteNet is superior to all methods and improves global routing accuracy by 50%

Circuit Name	FPR (%)	TPR (%)				
		TR	GR	LR	SVM	RouteNet
des_perf	0.54	17	56	54	42	74
edit_dist	1.00	25	36	38	28	64
fft	0.30	21	45	54	31	71
matrix_mult_a	0.21	13	30	34	12	49
matrix_mult_b	0.24	13	37	41	20	53
Average	0.46	18	41	44	27	62

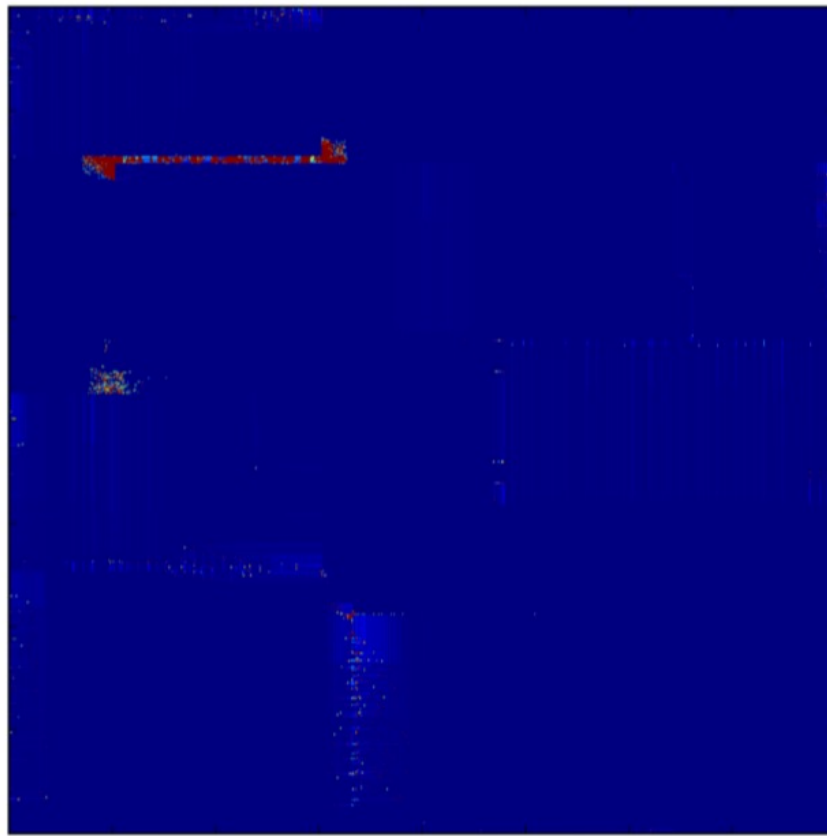
Label	Prediction Result		Evaluation
	Positive	Negative	
	Positive	Negative	
	TP	FN	$TPR = \frac{TP}{TP + FN}$
	Negative	TN	$FPR = \frac{FP}{FP + TN}$

TPR (True Positive Rate)
FPR (False Positive Rate)

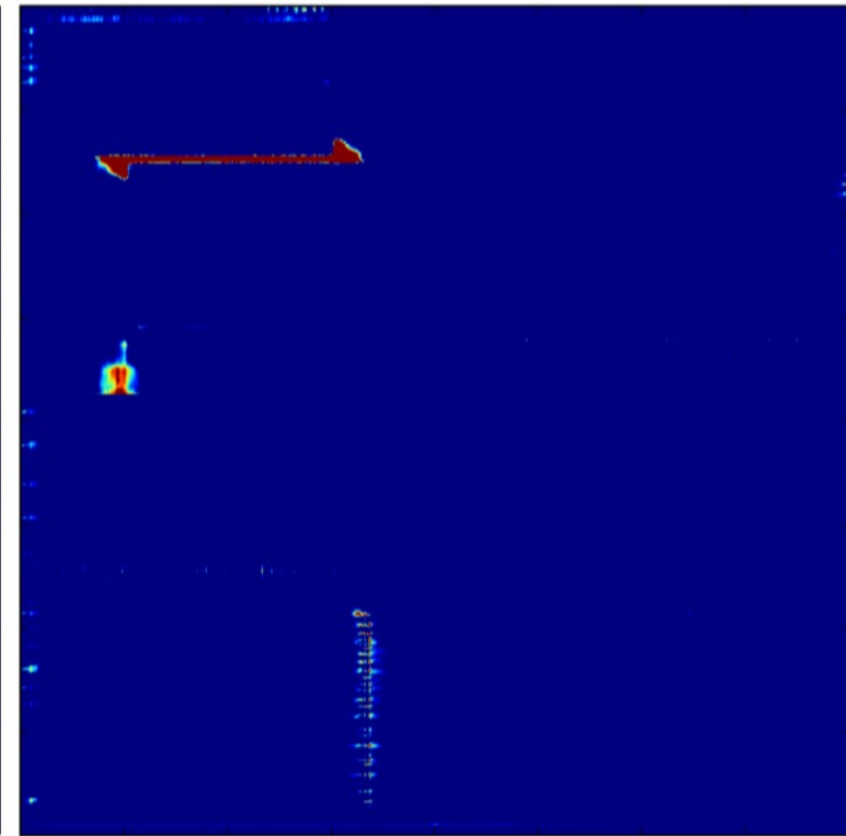
DRC Hotspot Detection Evaluation



LR



Ground Truth



RouteNet

DRC Hotspot Detection Evaluation

- Variations of FCN
 - Infer seen: Training and inference on different placements of the same circuit
 - Less data: Trained on data from less designs
 - No short: Shortcut structure is removed
 - Less conv: Three convolutional layers are removed
 - No pool: Pooling layers are removed

Circuit Name	FPR (%)	TPR (%)					Route Net
		Infer seen	Less data	No short	Less conv	No pool	
des_perf	0.54	77	71	71	73	68	74
edit_dist	1.00	68	61	63	62	55	64
fft	0.30	74	70	68	68	69	71
matrix_mult_a	0.21	51	46	45	45	45	49
matrix_mult_b	0.24	58	50	51	50	50	53
Average	0.46	66	60	60	60	57	62

Importance of large receptive region and global information.

DRC Hotspot Detection Evaluation

- Variations of baselines
 - 5×5: Use window size of 5×5 grid cells to capture neighboring features of each grid cell.
 - 9×9: 9 × 9 grid cells of window size.

Circuit Name	FPR (%)	TPR (%)					
		LR	5×5 LR	9×9 LR	SVM	5×5 SVM	9×9 SVM
des_perf	0.54	54	58	58	42	47	29
edit_dist	1.00	38	39	38	28	29	20
fft	0.30	54	56	54	31	41	23
matrix_mult_a	0.21	34	36	35	12	32	9
matrix_mult_b	0.24	41	44	42	20	39	16
Average	0.46	44	47	45	27	38	19

**Large receptive region
gives better results**

**But even larger window
blurs local information**

RouteNet is better choice

Conclusion

- We propose RouteNet:
 - Enables a global view for less homogeneous layout
 - Faster overall routability forecast at placement
 - More accurate hotspot detection at global routing

Thanks

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